

L Number	Hits	Search Text	DB	Time stamp
1	2617	(robot\$1 near5 assembl\$3).ab.	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/02/11 14:19
3	3	((robot\$1 near5 assembl\$3).ab.) and optic\$1.ab.) and cable\$1	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/02/11 14:19
2	6	((robot\$1 near5 assembl\$3).ab.) and optic\$1.ab.	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/02/11 14:21
4	79	((robot\$1 near5 assembl\$3).ab.) and optic\$.ab.	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/02/11 14:22
5	10	((robot\$1 near5 assembl\$3).ab.) and optic\$.ab.) and cable\$1.ab.	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/02/11 14:25
6	1	((((robot\$1 near5 assembl\$3).ab.) and optic\$.ab.) and cable\$1.ab.) and jumper.ti.	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/02/11 14:26
7	1	(((((robot\$1 near5 assembl\$3).ab.) and optic\$.ab.) and cable\$1.ab.) and jumper.ti.) and rotat\$	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/02/11 14:27
8	28	((robot\$1 near5 assembl\$3).ab.) and optic\$.ab.) and connect\$	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/02/11 14:28
9	27	((robot\$1 near5 assembl\$3).ab.) and optic\$.ab.) and connect\$3	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/02/11 14:30
10	9072	(robot\$ near arm).ab.	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/02/11 14:31
11	2	385/53-87	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/02/11 14:31
12	7274	(385/53-87).CCLS.	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/02/11 14:33
13	2	((robot\$ near arm).ab.) and ((385/53-87).CCLS.)	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/02/11 14:35
15	1	((robot\$ near arm).ab.) and ((385/53-87).CCLS.)) and (385/\$.ccls.and robot\$.ti.)	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/02/11 14:37
14	10	385/\$.ccls.and robot\$.ti.	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/02/11 14:37

10/082,799

BEST AVAILABLE COPY